

Learning Traffic Anomalies from Generative **Models on Real-Time Observations**

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Traffic Anomaly Detection Setup

- Detection of traffic anomalies \rightarrow crucial for:
 - Effective urban traffic management
 - Congestion mitigation
 - Responding to and preventing accidents
- Real-time, minute-by-minute observations from 42 traffic cameras across Gothenburg, Sweden
- Preprocessing \rightarrow **Flow** metric representing vehicle density: number of detected vehicles / maximum vehicle capacity

number of detected vehicles

flow =

maximum vehicle capacity

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STGAN Framework Capturing Spatiotemporal Features

- Results with Spatiotemporal Graph Convolutional Adversarial Network (STGAN)
- STGAN combines:
 - Graph Neural Networks (GNNs)
 - Long Short-Term Memory (LSTM)
- To capture complex spatial and temporal dependencies in traffic data

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STGAN Framework Generator and Discriminator

• Traffic network: weighted graph G = (V, E, W)

$$\mathbf{W}_{ij} = \begin{cases} \exp\left(-\frac{\operatorname{dist}(v_i, v_j)^2}{\sigma^2}\right), & \text{if } (i, j) \\ 0, & \text{otherw} \end{cases}$$

- Spatiotemporal Generator: Generates predicted sequences of traffic data
- Spatiotemporal Discriminator: Distinguishes between real and generated sequences

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STGAN Framework Generator Modules

- **Recent Module**: Captures short-term spatiotemporal dependencies using a Graph Convolutional Gated Recurrent Unit (**GCGRU**)
- **Trend Module**: Learns long-term temporal patterns using an LSTM network
- External Module: Incorporates external factors (e.g., time) of day, day of the week) using a fully connected layer
- These inputs are fused and passed through a Graph Convolutional Networks (GCN) to model spatial dependencies, generating a fake sequence
- The discriminator, using GCGRU and GCN modules, evaluates the generated sequence against real sequences

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STGAN Framework Anomaly Scores

- Anomalies are detected by comparing the generated data to the real data and assessing the discriminator's confidence
- Anomaly score: combine discriminator error and generator error

$$s_G(v, t) = \|G_{\theta}(v, t) - \mathbf{X}_{v,t}\|^2$$
$$s_D(v, t) = D_{\phi}(\mathbf{S}_{v,t}) - D_{\phi}(\hat{\mathbf{S}}_{v,t})$$
$$score(v, t) = s_G(v, t) + \lambda s_D(v, t)$$





Training Process STGAN Framework

- Preprocessing:
 - 5-minute **smoothing** of the data
 - **Patch** missing minutes (forward fill)
 - **Truncate** times < 4:53 am and > 9:00pm ullet
 - Calculation of node **distances**, node \bullet subgraphs and **time feature** (weekday, hour)
- **Training**: April to November 2020
- Validation: November 14–23, 2020 \bullet
- Repo: github.com/fgias/traffic-anomalydetection

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Traffic Anomaly Detection Evaluation

- Calculate the anomaly scores of all the data in the test set
- Label top K% anomaly scores as anomalies

lower K \leftrightarrow fewer false positives \leftrightarrow higher precision

true positives

precision =true positives + false positives

- Evaluating AD in real-world scenarios remains an open challenge
- Manually verify anomalies using unprocessed photos





 Model effectively detects traffic anomalies



Anomaly Type	Number of Anomal
Camera signal cut/restart	71
Visual artifacts	2
Extreme weather conditions	2
True positives	75
False positives	6
Total	81

Identified anomalies and anomaly types for K=0.1%





- Model effectively detects traffic anomalies
- Camera signal cut/restart → Signals due to problems with the functioning of the camera
- Visual artifacts → Anomalies triggered due to the visual quality of the input
- Extreme weather conditions \rightarrow Anomalies due to developments in the weather



Dry roads



Wet roads: water creates visual artifacts

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Identification of Anomalies for Cam25



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Camera signal cut/restart



Identification of Anomalies for Cam25



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Nov. 19, 2020, Cam14, **14:10**



Nov. 19, 2020, Cam14, **14:20**

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Identification of Anomalies for Cam25



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Nov. 19, 2020, Cam25, 14:15



Nov. 19, 2020, Cam25, **14:18**



Conclusion

Traffic Anomaly Detection

- Presented the **STGAN** Framework
- Combining GCNs and LSTMs
- Successfully identified spatial and temporal features
- Flagged traffic anomalies due to extreme weather

Future Work

- Enhancing model robustness against visual artifacts
- Optimizing hyperparameter selection for different urban contexts

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Thank you!



